

Q1 (5 points). For the control system of figure (1),

$$G(s) = \frac{1}{(s+2)(s+3)}, C(s) = K$$

and $H(s) = \frac{1}{(s+1)}$. Find :

- The overall transfer function.
- The open loop transfer function.
- The characteristic equation of this system.
- The values of the gain K that keeps this control system stable.

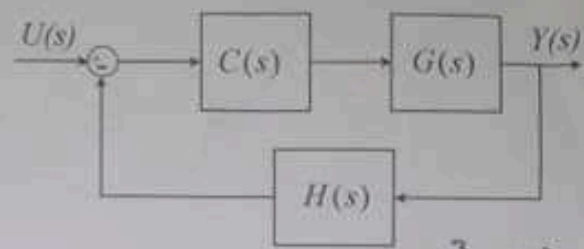


Figure (1)

$$s^3 + 6s^2 + 11s + 6 = 0$$

Q2 (3 points). Find the overall transfer function of the control system of figure (2).

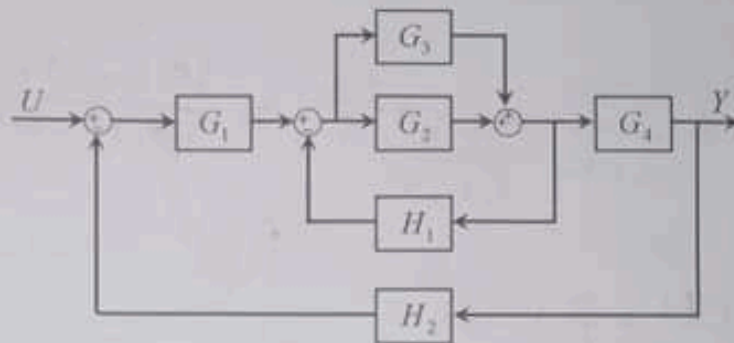


Figure (2)

Q3 (4 points). Consider the liquid storage tank schematized as in figure (3). The differential equation describing the behaviour of this system is given as $h'(t) = K_1(F_{in}(t) - F_{out}(t))$. The output flow rate is given as $F_{out}(t) = K_2 h(t)$. (K_1 and K_2 are constants)

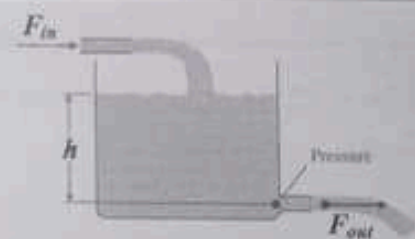


Figure (3)

- Find the transfer function that relates h to F_{in} with the initial condition $h(0) = 0$.
- If the input F_{in} is a unit step signal express the output signal ($h(t)$) as a function of time.

Q4 (4 points). For the control system of the figure (4-a), $G_c(s) = K$ and

$$G(s) = \frac{2}{(s+b)}$$

signal $U(s) = \frac{10}{s}$ gives the output signal

plotted in figure (4-b). Find:

- The overall transfer functions of the system.
- The values of K and b .
- The expression of the error signal as a function of time $e(t)$.
- The position error coefficient (K_p) of the system.

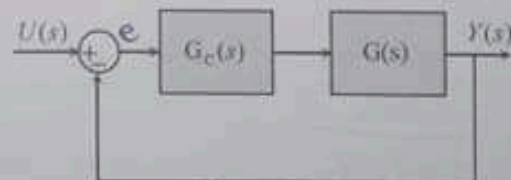


Figure (4-a)

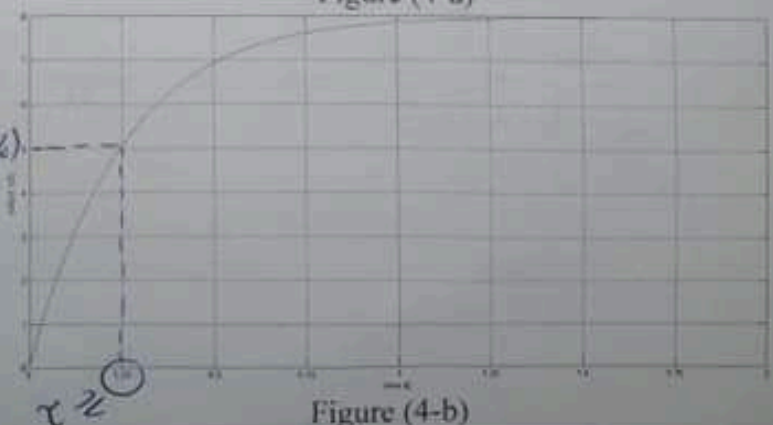


Figure (4-b)